

Determining SUSY Parameters at the LHC

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The LHC Inverse Problem

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In principle straightforward, at least for weakly interacting theories; is being automatized.

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 - **Find the right theory** responsible for the signal(s)?
 - **Determine the values of the free parameters** of this theory?

Application to MSSM

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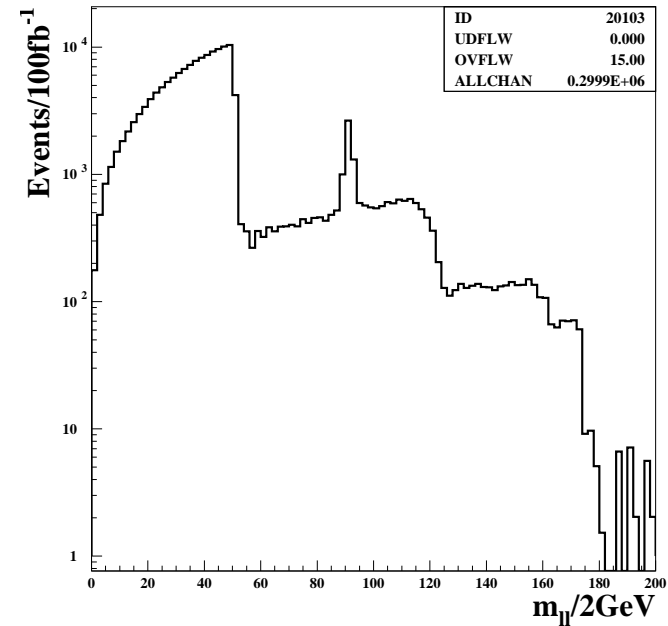
Good theory for trying out methods of parameter determination!

Traditional Approach to Parameter Determination

Determine (differences of) masses directly from kinematic features, e.g. $m_{\ell^+\ell^-}$ edges from $\tilde{\chi}_i^0 \rightarrow \tilde{\chi}_j^0 \ell^+ \ell^-$

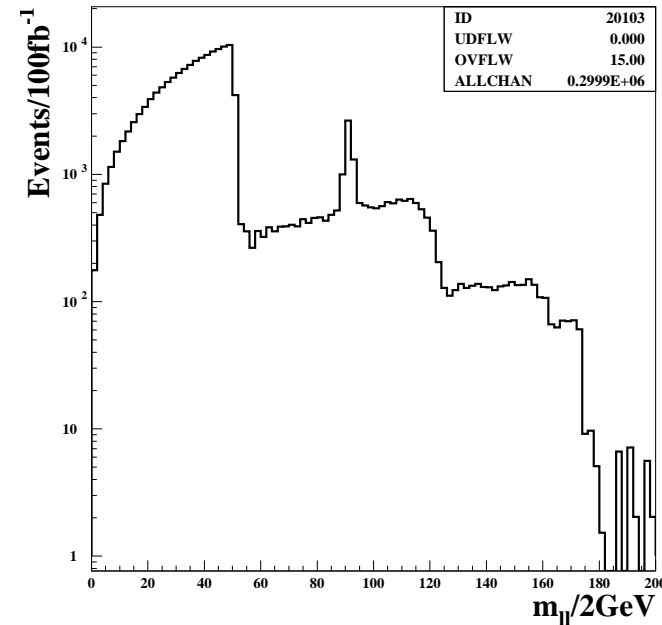
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Once sufficiently many (differences of) masses are known: fit parameters in Lagrangian ($\overline{\text{DR}}$ renormalized soft breaking parameters). Hinchliffe et al. 1996, ...

Advantages of Traditional Approach

- First step (kinematic fitting) is **quite model independent.**
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- Second step, and in simple cases also first step, does not need event generation / simulation
⇒ **Small numerical effort needed**

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- Works very well only for final states containing ≥ 2 charged leptons $\ell^\pm = e^\pm, \mu^\pm$; in large parts of (C)MSSM parameter space, these are very rare.

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- Uses only small fraction of available information: wasteful!

Brute-Force Approach

Arkani-Hamed, Kane, Thaler, Wang 2005

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 - Distributions: Divide in $n \in \{10, 20\}$ bins such that each bin contains same no. of events; observables are bin boundaries
- Randomly generated 43,026 MSSM spectra in 15-parameter MSSM; found 283 “degenerate pairs”
- Statistics employed highly questionable!

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- **Keep control of statistical properties:** include full covariance matrix

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- \implies **take 84 observables**

Construction of Observables

- Divide all events into 12 mutually exclusive classes:

($l = e, \mu$)

1: $0l$; 2: $1l^-$; 3: $1l^+$; 4: $2l^-$; 5: $2l^+$; 6: $l_i^+ l_i^-$; 7: $l_i^+ l_{j \neq i}^-$;

8: $l_i^- l_j^- l_j^+$; 9: $l_i^+ l_j^- l_j^+$; 10: $l_i^- l_j^- l_{k \neq i, j}^\pm$ for +; 11: $l_i^+ l_j^+ l_{k \neq i, j}^\pm$ for -;

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- Define 7 observables within each class of events:

$O_{1,c} = n_c/N$; $O_{2,c} = \langle n_{\tau^-} \rangle_c$; $O_{3,c} = \langle n_{\tau^+} \rangle_c$;
 $O_{4,c} = \langle n_b \rangle_c$; $O_{5,c} = \langle n_j \rangle_c$; $O_{6,c} = \langle n_j^2 \rangle_c$; $O_{7,c} = \langle H_T \rangle_c$
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- Cuts depend on event class

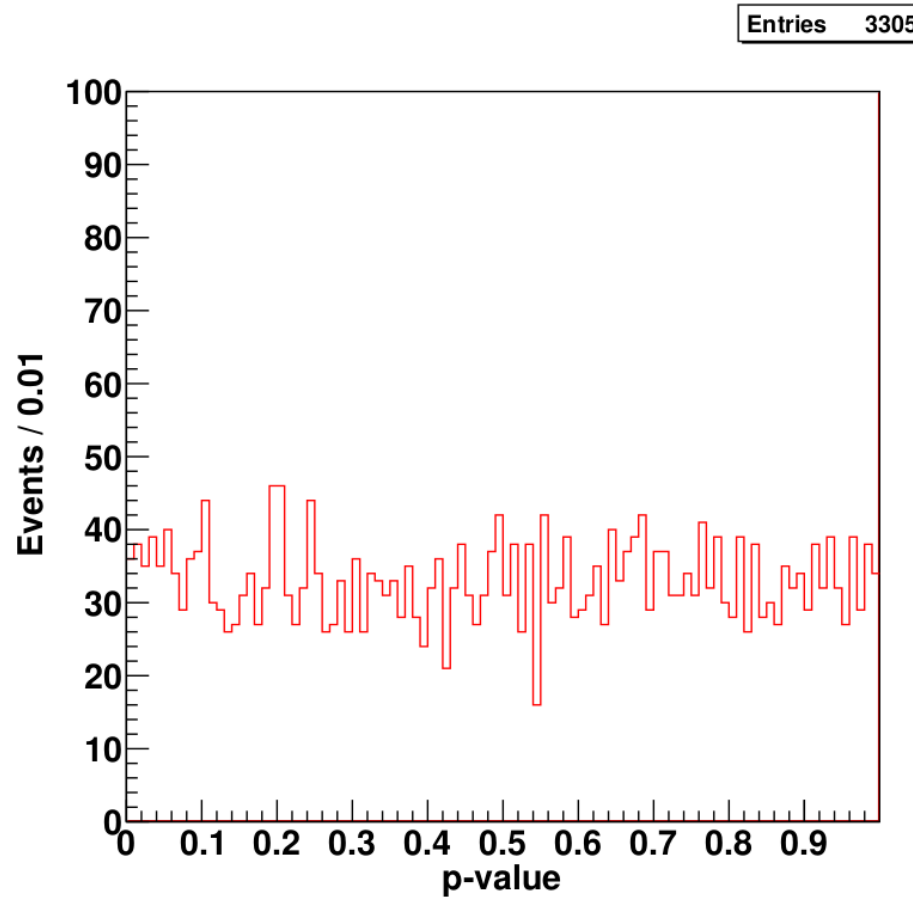
Discriminating between Scenarios

arXiv:1206.6080 (hep-ph)

Based on $\chi_{AB}^2 = \sum_{m,n=1}^{N_{O,\max}} (O_m^A - O_m^B) (V^{-1})_{mn} (O_n^A - O_n^B)$

Include only “significant” observables ($\implies N_{O,\max} < 84$ usually), based on ≥ 10 events

Distribution of total p -value



Based on self-comparison of 3,305 scenarios of Arkani-Hamed et al.

Results

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- With SM background and syst. errors: 237 “degenerate pairs” have $p < 0.05$

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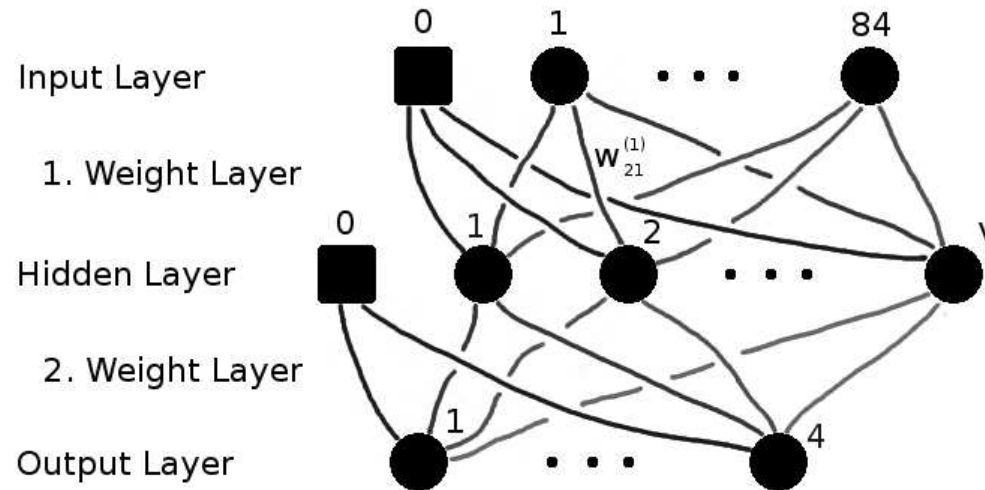
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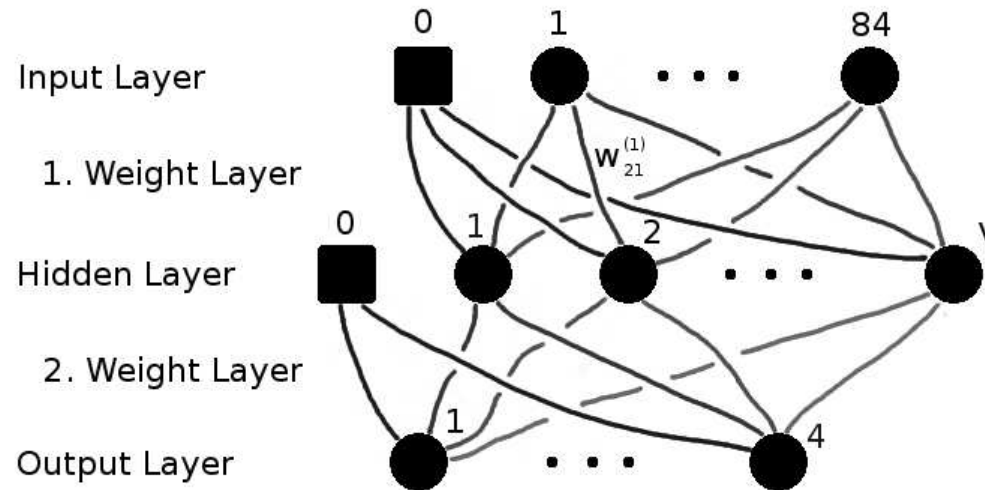
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Best effort gave estimated errors two times larger than better method.

Artificial Neural Networks

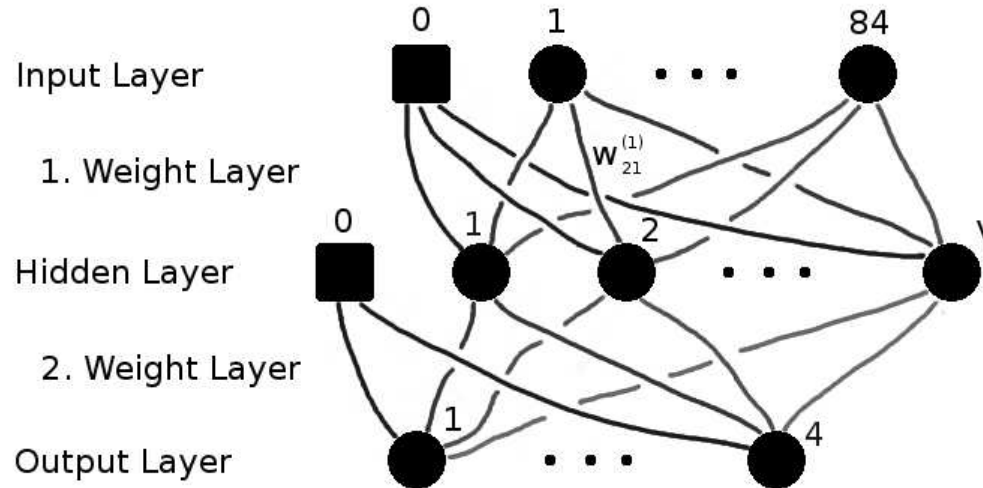


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84(+1) input neurons: pass on **normalized observables**
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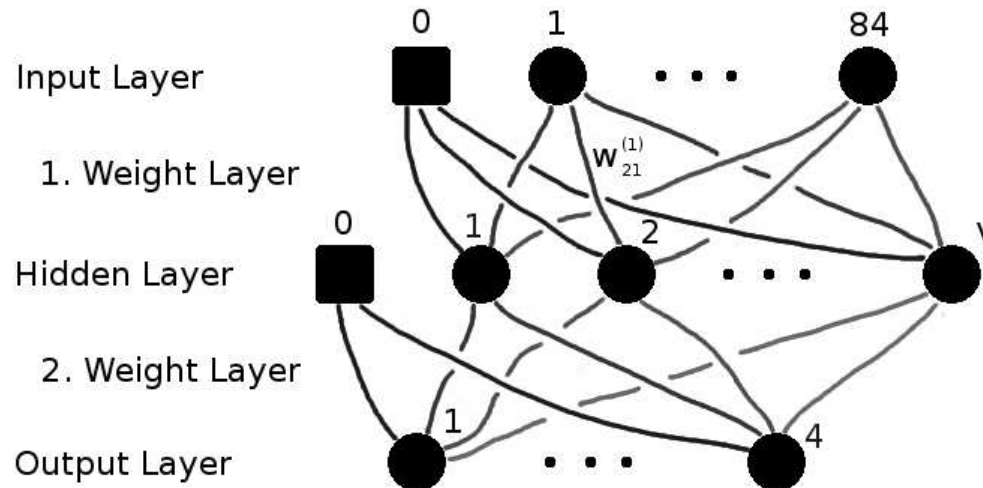
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1 output neuron: outputs **normalized CMSSM parameter** $y \in [-1, +1]$.

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Form of $\tanh \implies$ ANN is good at interpolating, not necessarily at extrapolating

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Determine “optimal” values of weights $w_{ai}^{(1)}$, $w_a^{(2)}$:
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Considered 4 benchmark points just beyond current limits; used reduced parameter range for m_0 , $m_{1/2}$ when constructing training and control sets:

$$m_{1/2} \in [m_{1/2}^{\text{true}} - 40 \text{ GeV}, m_{1/2}^{\text{true}} + 40 \text{ GeV}]$$

$$m_0 \in [m_0^{\text{true}} - 150 \text{ GeV}, m_0^{\text{true}} + 150 \text{ GeV}] \text{ (roughly).}$$

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Generated $\sim 1,000$ (primary) training sets, 300 control sets for each benchmark point

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This implies:

Different inputs (observables) can give same output (CMSSM parameter);

Same inputs can give different outputs, in training sets!

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- Improves ANN performance by 15 to 30%
- Improves statistical properties of output: can derive reliable Gaussian error estimates!

ANN training: iterative

- In each step, change weights such that totality of *training sets* is described better, i.e.

$$\sum_{i=1}^{N_{\text{train}}} [y(O_i) - y_i]^2$$

is reduced (“conjugate gradient algorithm”)

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- Stop iteration when normalized control error has reached minimum:

$$\bar{F}^2 = \frac{\sum_{i=1}^{N_{\text{control}}} [y(O_i) - y_i]^2}{\sum_{i=1}^{N_{\text{control}}} [y_i - \bar{y}]^2}$$

Recall: control sets not used for modifying weights!

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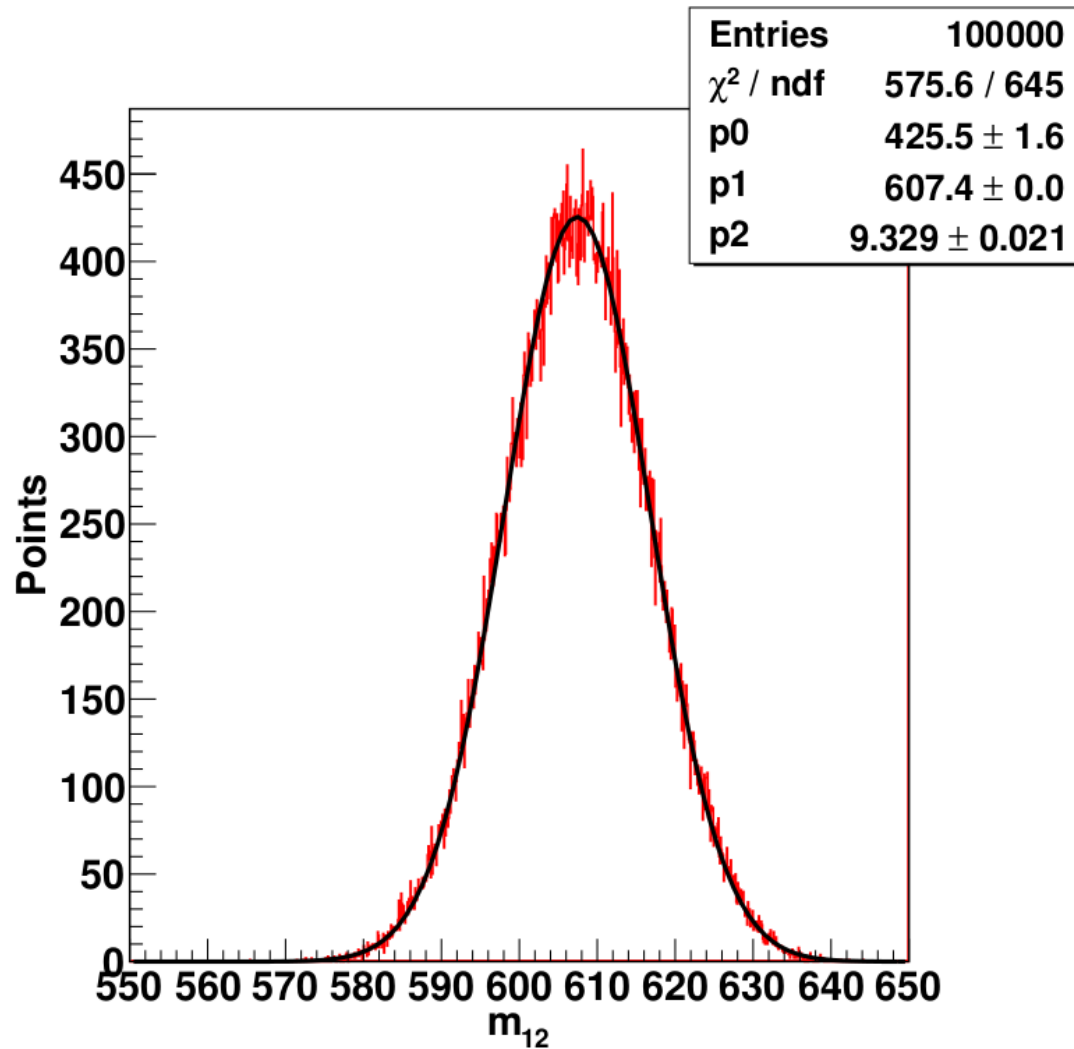
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Both methods give consistent results!

Example: BP3 with 10 fb^{-1}



From error propagation: $m_{1/2} = 607 \pm 11 \text{ GeV}$.

Results

	Point 1	Point 2	Point 3	Point 4
	10/fb			
m_0	171.47 ± 34.53	1998.93 ± 92.20	1055.97 ± 47.26	482.94 ± 61.23
$m_{1/2}$	697.41 ± 7.76	446.55 ± 11.30	607.45 ± 11.53	695.48 ± 7.88
$\tan \beta$	21.35 ± 5.96	12.34 ± 20.17	23.41 ± 37.42	26.00 ± 10.66
A_0	463.43 ± 326.00	1406.37 ± 2898.67	1453.49 ± 1891.58	-73.52 ± 628.16
	500/fb			
m_0	156.40 ± 4.88	2004.05 ± 10.61	1015.66 ± 4.49	391.86 ± 7.70
$m_{1/2}$	701.17 ± 0.87	451.15 ± 1.00	598.75 ± 1.21	700.71 ± 0.88
$\tan \beta$	9.39 ± 0.70	14.30 ± 2.12	20.79 ± 5.20	30.54 ± 1.23
A_0	-43.61 ± 55.37	261.47 ± 474.68	774.39 ± 295.63	183.05 ± 101.48

All correlations are quite weak

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